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On algebraic minimal surfaces

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Contents of this talk

- overview on classical results
- techniques: Björling, Weierstraß, ...
- Enneper, Bour, Henneberg, Richmond
- Möbius type minimal surface, minimal double surfaces
- low degree examples
- open problems

Classical results

[1,4,6,7,8,9,20,22,25,27,28,29,31]

not algebraic: Helicoid, Catenoid, Scherk, . . . though related to some algebraic surfaces

Geiser's surface \mathcal{G} and Lie's surface \mathcal{L} : lowest possible degree, **but not real!**

$$\mathcal{L}: 2(x-iy)^3 - 6i(x-iy)z - 3(x+iy) = 0, \quad \mathcal{G}: (x-iy)^4 + 3(x^2+y^2+z^2) = 0$$

their duals

$$\mathcal{L}^*: 27w_0(w_2+iw_1)^2 + 9i(w_1^2+w_2^2)w_3 - 4iw_3^3 = 0, \quad \mathcal{G}^*: 9w_0^2(w_1-iw_2)^4 - (w_1^2+w_2^2+w_3^2)^3 = 0$$

Their classes and degrees do not follow the rules for real minimal surfaces:

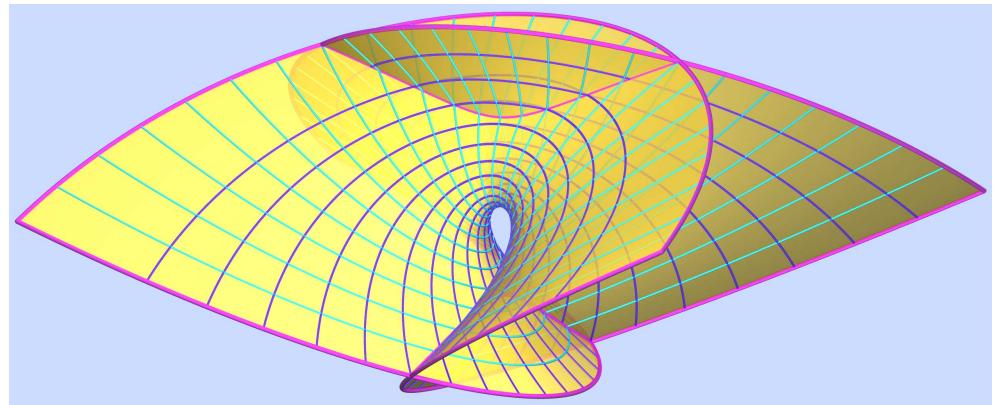
$$\deg \mathcal{L} = \text{cl } \mathcal{L} = \deg \mathcal{L}^* = 3 \quad \deg \mathcal{G} = 4, \quad \text{cl } \mathcal{G} = \deg \mathcal{G}^* = 6.$$

for real minimal surfaces [22]:

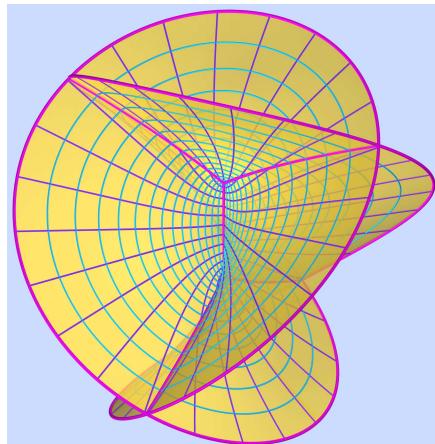
Theorem. The sum of the degree and class of a **real** minimal surface is at least 15.

Classical results

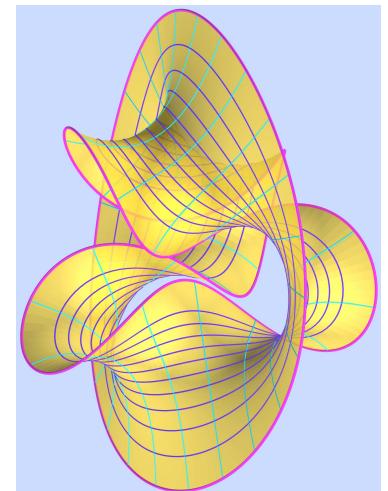
Enneper's surface is minimal in two ways: $\deg = 9$, $\text{cl} = 6$; $6+9=15$; and minimal in the differential geometric sense [5,22]



Henneberg's surface is of minimal class (among the real minimal surfaces): $\text{cl} = 5$, $\deg = 15$ [10,11,22]



Richmond's surface: up to equiform transformations the only real minimal surface of $\deg = 12 = \text{cl}$ [28]



Parametrization techniques - formulae by Weierstraß

[2,16,20,25,32]

$A, B : D \subset \mathbb{C} \rightarrow \mathbb{C}$ meromorphic functions, $w = u + iv$... complex parameter in D

$$f(u, v) = \Re \int \begin{pmatrix} A(1 - B^2) \\ iA(1 + B^2) \\ 2AB \end{pmatrix} dw \quad \text{or} \quad f(u, v) = \Re \int \begin{pmatrix} G^2 - H^2 \\ i(G^2 + H^2) \\ 2GH \end{pmatrix} dw$$

with $A = G^2$ and $B = HG^{-1}$ ($G \neq 0$) yields parametrizations of minimal surfaces.

Merely inserting algebraic functions does not necessarily result in algebraic minimal surfaces.

Bour's surfaces: $A(w) = cw^{n-2}$, $c \in \mathbb{C} \setminus \{0\}$, $n \in \mathbb{Z} \setminus \{0\}$ and $B(w) = w$

Enneper's surfaces: $A(w) = 1$, $B(w) = w^n$

Richmond's surfaces: $A(w) = \frac{1}{w^2}$, $B(w) = w^{2n}$

Parametrization techniques - formulae by Weierstraß

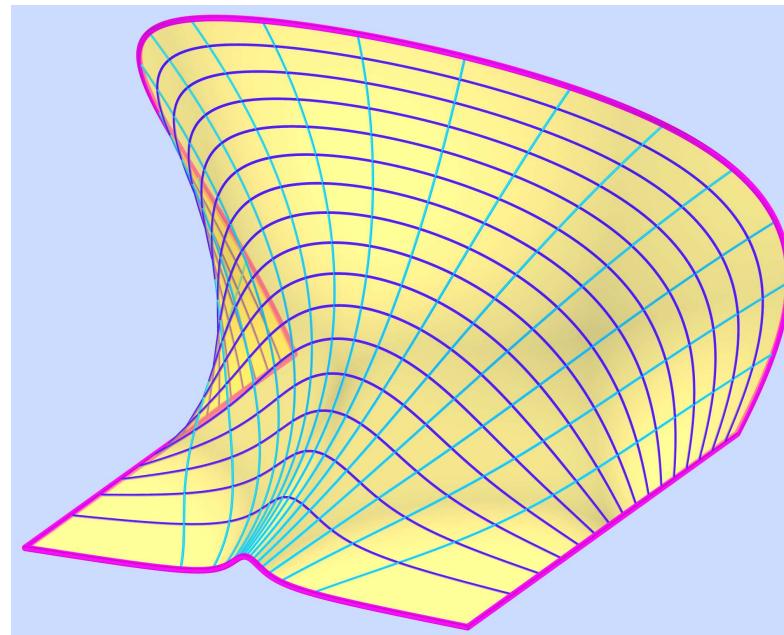
$\mathcal{B}(1, 0) = \mathcal{E}(-1)$... catenoid, $\mathcal{B}(i, 0)$... helicoid

$\mathcal{B}(1, 2), \mathcal{B}(i, 2)$... Enneper's surface $\mathcal{E}(1)$ up to equiform transformations

$\mathcal{E}(-2) = \mathcal{R}(1)$

$\mathcal{E}(0), \mathcal{R}(0)$... flat

$\mathcal{B}(1, 1), \mathcal{B}(i, 1)$... not algebraic, but worth an inspection



Parametrization techniques - formulae by Weierstraß

[20,22,32]

integral free representation of minimal surfaces

$$f(u, v) = \Re e \begin{pmatrix} (1-w^2)A'' + 2wA' - 2A \\ i(1+w^2)A'' - 2iwA' + 2iA \\ 2wA'' - 2A' \end{pmatrix} \quad (*)$$

$A(w): D \subset \mathbb{C} \rightarrow \mathbb{C}$... meromorphic function

with derivatives $A' = \frac{dA}{dw}$, $A'' = \frac{d^2A}{dw^2}$, $A''' = \frac{d^3A}{dw^3}$

$$\mathbf{i} = \begin{pmatrix} 1 - w^2 \\ i(1 + w^2) \\ 2w \end{pmatrix} \dots \text{isotropic vector in } \mathbb{R}^3, \text{ i.e., } \langle \mathbf{i}, \mathbf{i} \rangle = 0$$

define $\mathbf{j} = A''\mathbf{i} - A'\mathbf{i}' + A\mathbf{i}''$; elementary to verify: $\langle \mathbf{j}', \mathbf{j}' \rangle = 0$, and thus, \mathbf{j}' is isotropic

Therefore, $\Re e \mathbf{j} = f$ from $(*)$ is a real parametrization of a real minimal surface.

Theorem. Each algebraic function $A: D \subset \mathbb{C} \rightarrow \mathbb{C}$ with $A''' \not\equiv 0$ in D yields an algebraic minimal surface parametrized by $(*)$.

Parametrization techniques - Björling's Formula

$\gamma : I \subset \mathbb{R} \rightarrow \mathbb{R}^3$... spine curve, $\nu : I \rightarrow S^1$... unit normal vector field along γ

Both are considered to have a complex continuation.

$$\varphi(t) = \gamma - i \int_{t_0}^t \nu(\tau) \times d\gamma(\tau)$$
 ... isotropic curve, i.e., a curve of constant slope $\pm i$

Complex continuation: Let $t = u + iv$ and then

$$f(u, v) = \operatorname{Re}(\varphi)$$

is a real parametrization of the minimal surface on the scroll (γ, ν) .

$$f^\perp(u, v) := \operatorname{Im}(\varphi)$$

is the adjoint minimal surface to f .

Associate family f_τ of minimal surfaces

$$f_\tau = \operatorname{Re}(e^{i\tau} \varphi(t)), \quad f = f_0, \quad f^\perp = f_{\frac{\pi}{2}}$$

Theorem. The associate minimal surfaces to an algebraic minimal surface are algebraic.

Parametrization techniques - Björling's Formula

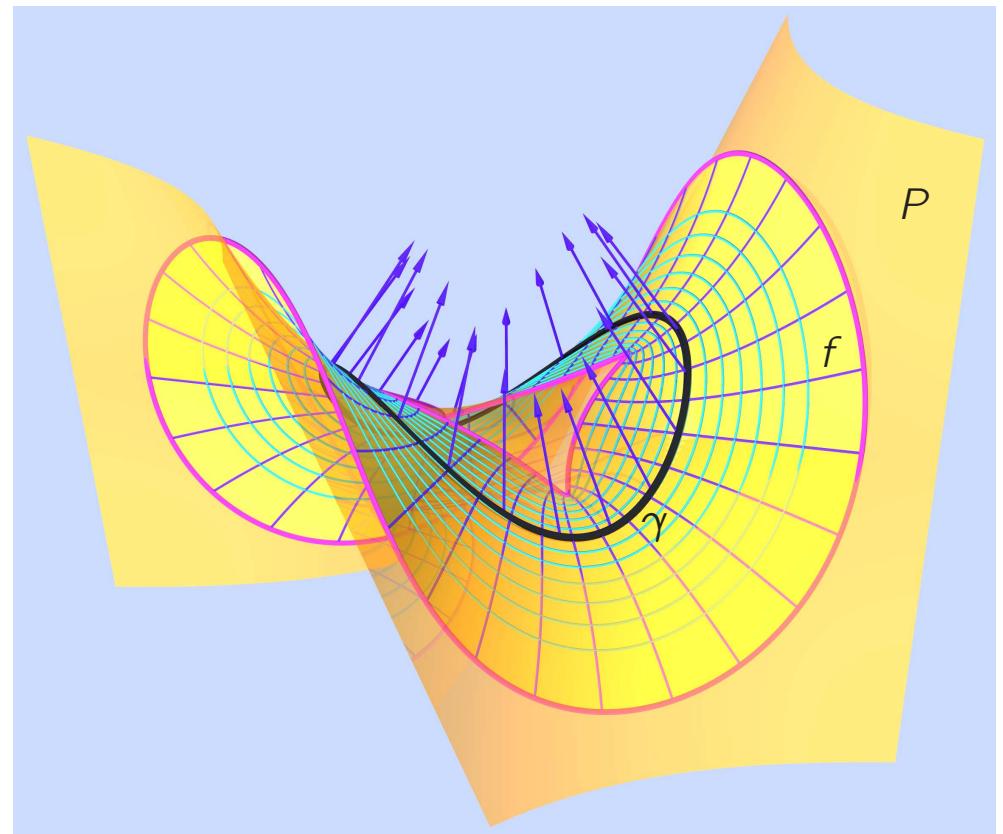
Theorem. Let γ be the evolute of an algebraic curve contained in an algebraic cylinder Z . The minimal surface tangent to Z along γ is algebraic. [12,20,22]

This theorem gives only a few examples, but:

Replace Z by an orthogonal hyperbolic paraboloid P : $(1-b^2)xy=2bz$, $b \neq \pm 1$ and $\gamma = P \cap Z$ with $Z: x^2 + y^2 = 1$.

Such curves γ are curves of constant Gaussian curvature on P .

Theorem. The minimal surfaces f that touch an orthogonal hyperbolic paraboloid P along the curves of constant Gaussian curvature are rational (and thus algebraic) minimal surfaces of degree 30 with the parametrization ...



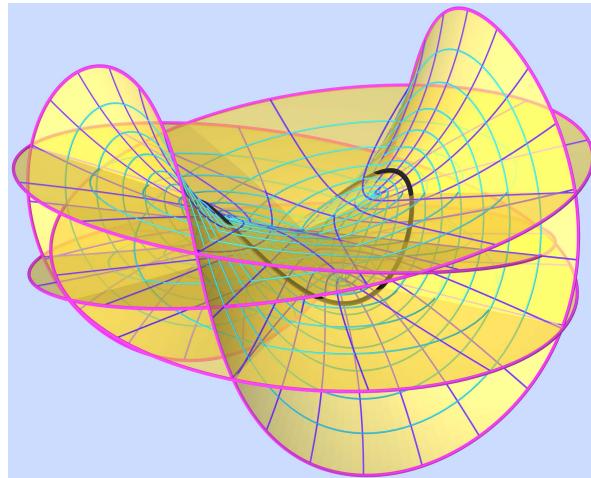
Parametrization techniques - Björling's Formula

$$\dots f(u, v) = \frac{1}{12b\beta_1} \begin{pmatrix} \beta_2^2 c_{3u} S_{3v} + 3c_u(\beta_3 S_v + 4b\beta_1 C_v) \\ -\beta_2^2 s_{3u} S_{3v} + 3s_u(\beta_3 S_v + 4b\beta_1 C_v) \\ 3\beta_2 s_{2u}(\beta_1 C_{2v} + 2bS_{2v}) \end{pmatrix} \text{ with} \\ \beta_1 := 1+b^2, \beta_2 := 1-b^2, \beta_3 := b^4+6b^2+1.$$

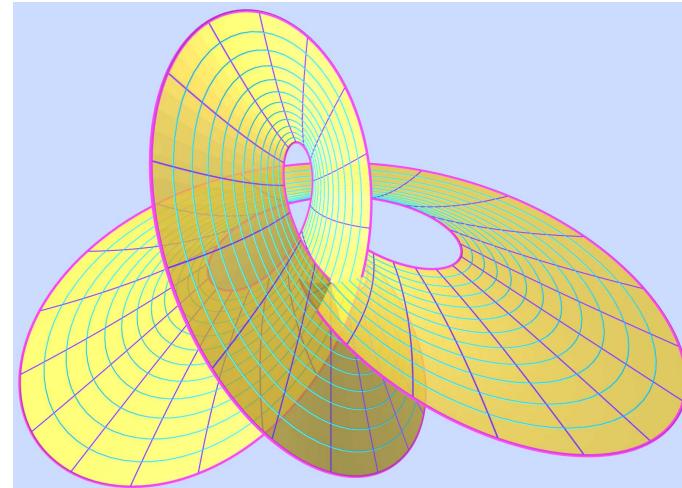
For a curve to a prescribed Gaussian curvature $K < K_{\max} = -\frac{\beta_2^2}{16b^4}$,

the radius r of Z fullfills

$$r^2 = \frac{1}{\beta_2 \sqrt{-K}} - \frac{4b^2}{\beta_2^2}.$$



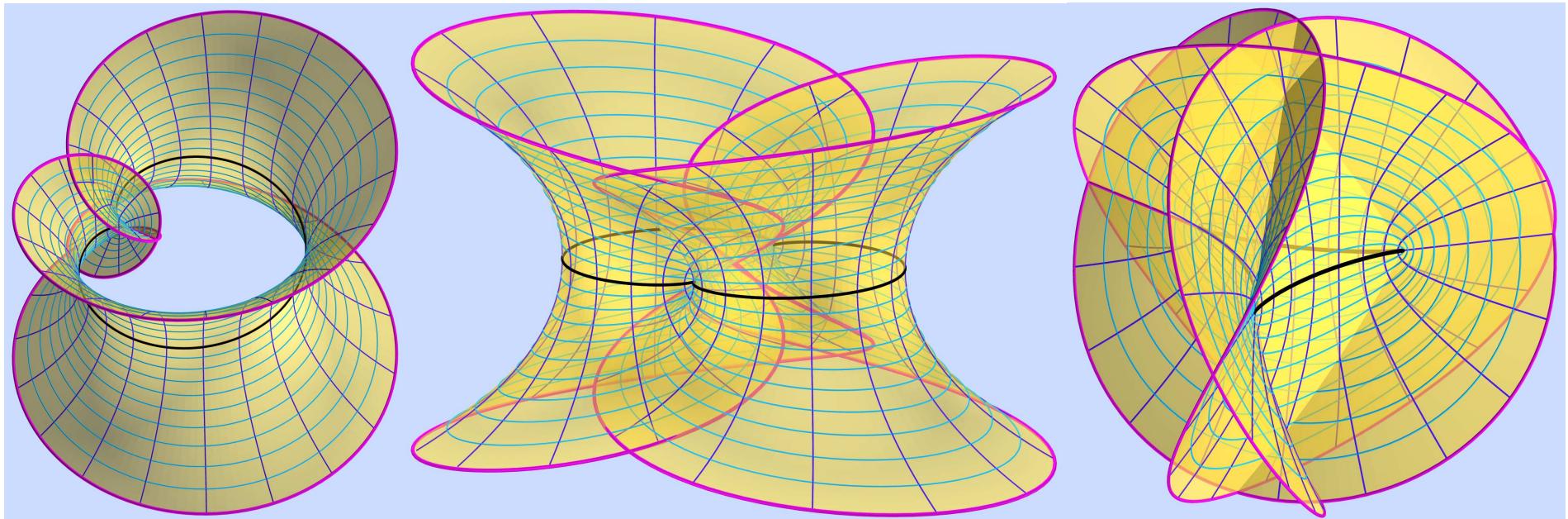
$$\leftarrow f \\ f^\perp \rightarrow$$



Parametrization techniques - Björling's Formula

Theorem. Let γ, ν_γ be a planar algebraic curve and its unit normal vector field. The minimal surface S on the scroll (γ, ν_γ) is algebraic, γ is a planar geodesic on the minimal surface, and the plane of γ is a plane of symmetry of S . [20]

This leads to cycloidal minimal surfaces (apparently new):



Not to be mixed up with Catalan's surface which is not algebraic!

Parametrization techniques - Björling's Formula - cycloidal minimal surfaces

Theorem. Let $r, R \in \mathbb{R} \setminus \{0\}$ be real constants with $R + 2r \neq 0$ and $R + r \neq 0$.

The minimal surfaces on the scroll (ζ, ν) with $\zeta \subset \pi_3$ and $\nu \in S^1$

$$\zeta(t) = \begin{pmatrix} (R+r)c_t + rc_{\frac{(R+r)t}{r}} \\ (R+r)s_t + rs_{\frac{(R+r)t}{r}} \\ 0 \end{pmatrix}, \quad \nu(t) = \frac{1}{2c_{\frac{Rt}{2r}}} \begin{pmatrix} -c_t - c_{\frac{(R+r)t}{r}} \\ -s_t - s_{\frac{(R+r)t}{r}} \\ 0 \end{pmatrix}$$

can be parametrized by

$$f(u, v) = \begin{pmatrix} (R+r)c_u C_v + rc_{\frac{(R+r)u}{r}} C_{\frac{(R+r)v}{r}} \\ (R+r)s_u C_v + rs_{\frac{(R+r)u}{r}} C_{\frac{(R+r)v}{r}} \\ -\frac{4r(R+r)}{R} c_{\frac{Ru}{2r}} S_{\frac{Rv}{2r}} \end{pmatrix}.$$

These minimal surfaces are algebraic, rational, and closed if, and only if, $R, r \in \mathbb{Q} \setminus \{0\}$.

In any case, the cycloid $\zeta \subset \pi_3$ is a geodesic on the minimal surface.

The surfaces with $R, r \in \mathbb{Q} \setminus \{0\}$ contain at least one straight line.

Cycloidal minimal surfaces & curves of constant slope

[3,5,13,15,26,36]

The cycloid ζ is of constant slope ($\sigma = 0$):

Theorem.

Moving through the associate family bends the curve ζ smoothly into curves of constant slope on the quadrics

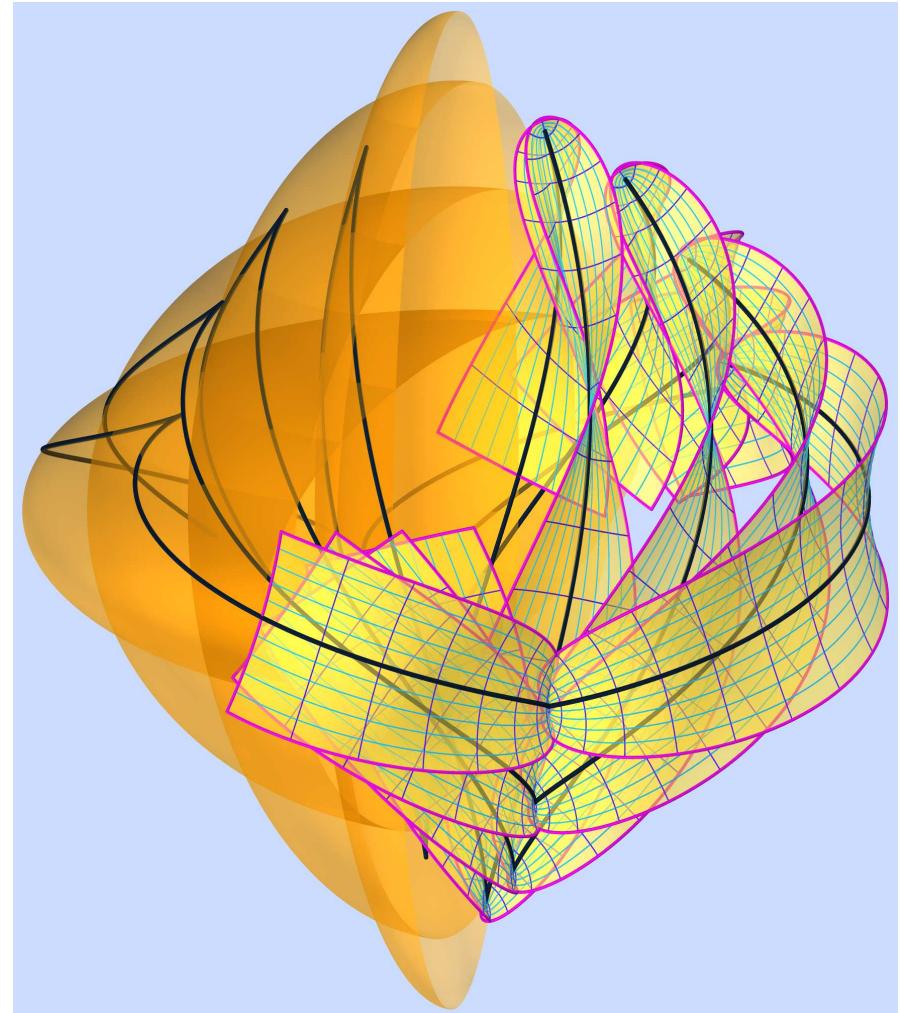
$$Q: x^2 + y^2 + \frac{R^2 \operatorname{ctg}^2 \tau}{4r(r+R)} z^2 = (2r+R)^2 \cos^2 \tau.$$

The slope angle σ is independent of R and r and is related to τ by

$$\cos \sigma = -\sin \tau \iff \sigma = \tau + \frac{\pi}{2} \pmod{2\pi}.$$

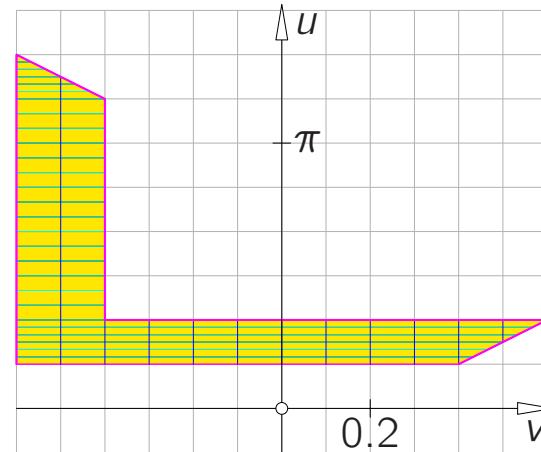
Theorem.

The u -lines on the cycloidal minimal surfaces are generalized oscillation curves. [26]

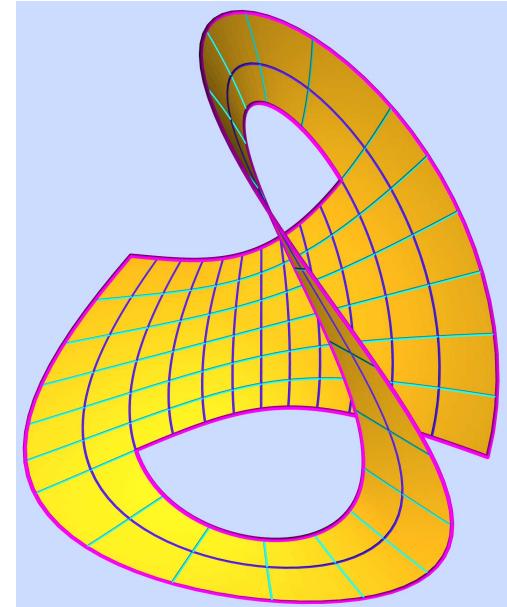


Minimal Möbius strips

Henneberg's surface is not orientable!
minimal double surface
(cf. [10,11,12])



Mapping an L-shaped domain in the parameter plane to the surface yields a Möbius strip on Henneberg's surface. (cf. [22])



Minimal Möbius strips - via Björling

$$\gamma(t) = (\cos t, \sin t, 0),$$

$$\nu(t) = (\cos t \cos \frac{t}{2} \sin t \cos \frac{t}{2}, \sin \frac{t}{2})$$

yields a rational minimal surface
of degree 11, class 22, and genus 1.

details: see [23]

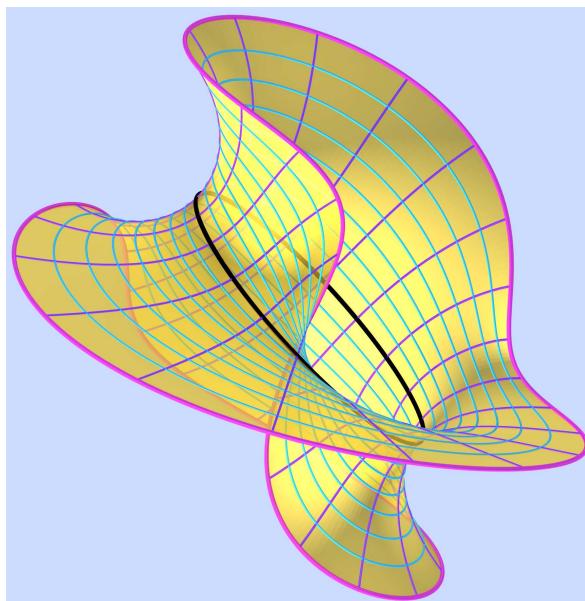
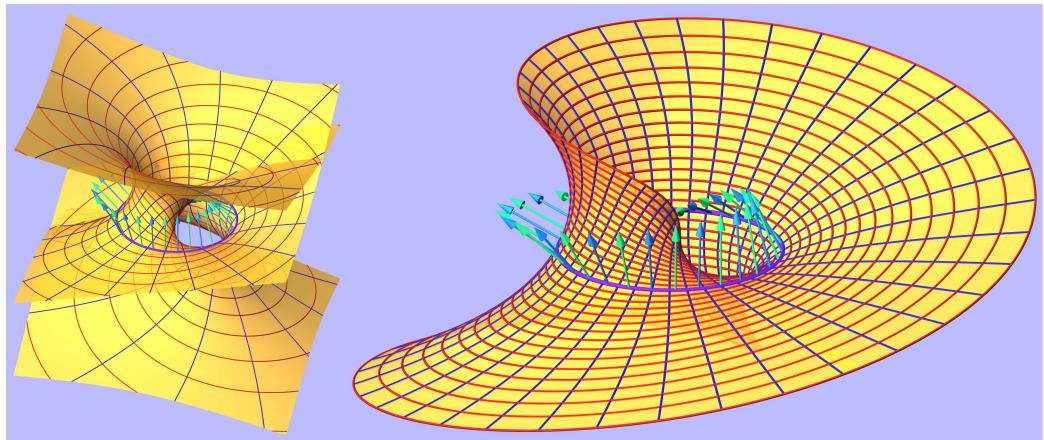
tangent to Krames's surface cf. [18]

rotoidal cf. [13,23]

$$\gamma(t) = (\cos t, \sin t, \sin t),$$

$$\nu(t) = (\cos t \cos \frac{t}{2} \sin t \cos \frac{t}{2}, \sin \frac{t}{2})$$

yields a rational minimal surface
of degree 35, class ≈ 70 , and genus 1.



Some remarks

- equation (\star) with $A = \sqrt{w} \implies f$ is algebraic, degree ?, implicit equation ??
- relations to isotropic congruences of lines: central envelope is minimal, rational, . . .
[14,17,24,27,30]
- degrees grow rapidly:
 $\deg \mathcal{B}(c, n) = (n + 1)^2$, $\deg \mathcal{E}(n) = (2n + 1)^2$, $\deg \mathcal{R}(n) = 2n(n + 1)$
- Parametrization formulae involving integrals should be handled with care.
Antiderivatives of algebraic functions need not be algebraic.
- Only Björling's formula with geometric ideas leads to low degree examples.
Proper curves may be found in [19,21,33–36].

Thank You For Your Attention!

Related work

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